

Compact plastic limit switches with positive opening mechanism

LJK-N Series

Positive opening mechanism meets standards worldwide. A wide variety of actuators is available.



Positive opening mechanism



■ The LJK-N conforms to IEC standards, and is certified by UL and CSA. (excluding some models) For equipment and facilities to be exported anywhere in the world, use the LJK-N with confidence.

■ Positive opening mechanism forces contacts open.*
 • Can prevent problems caused by contact fusing.
 • Can be used also as a safety limit switch.

■ Wide variety, with 33 catalog listings in the lineup

• Actuators: 11 types

• Contact configuration

Snap action: N.C. x 1 + N.O. x 1

Slow action: N.C. x + N.O. x 1 (BBM: break before make), N.C. x 2

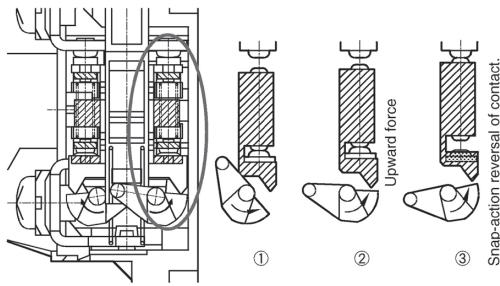
*Except for the steel wire and spring rod types.

CATALOG LISTING

Type of actuator	Internal switch mechanism	Contact configuration	Catalog listing
Resin roller lever	Snap action	N.C. x 1 + N.O. x 1	LJK-N2118F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2518F12
	Slow action	N.C. x 2	LJK-N2718F12
Resin adjustable roller lever	Snap action	N.C. x 1 + N.O. x 1	LJK-N2145F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2545F12
	Slow action	N.C. x 2	LJK-N2745F12
50 mm dia. resin roller lever	Snap action	N.C. x 1 + N.O. x 1	LJK-N2139F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2539F12
	Slow action	N.C. x 2	LJK-N2739F12
50 mm dia. resin adjustable roller lever	Snap action	N.C. x 1 + N.O. x 1	LJK-N2149F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2549F12
	Slow action	N.C. x 2	LJK-N2749F12
Plunger	Snap action	N.C. x 1 + N.O. x 1	LJK-N2110F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2510F12
	Slow action	N.C. x 2	LJK-N2710F12
Resin roller plunger	Snap action	N.C. x 1 + N.O. x 1	LJK-N2102F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2502F12
	Slow action	N.C. x 2	LJK-N2702F12
Resin cross roller plunger	Snap action	N.C. x 1 + N.O. x 1	LJK-N2103F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2503F12
	Slow action	N.C. x 2	LJK-N2703F12
Resin one-way roller (horizontal)	Snap action	N.C. x 1 + N.O. x 1	LJK-N2121F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2521F12
	Slow action	N.C. x 2	LJK-N2721F12
Resin one-way roller (vertical)	Snap action	N.C. x 1 + N.O. x 1	LJK-N2127F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2527F12
	Slow action	N.C. x 2	LJK-N2727F12
Steel wire	Snap action	N.C. x 1 + N.O. x 1	LJK-N2106F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2506F12
	Slow action	N.C. x 2	LJK-N2706F12
Spring rod	Snap action	N.C. x 1 + N.O. x 1	LJK-N2108F12
	Slow action BBM	N.C. x 1 + N.O. x 1	LJK-N2508F12
	Slow action	N.C. x 2	LJK-N2708F12

■ INTERNAL SWITCH

● Snap-action type

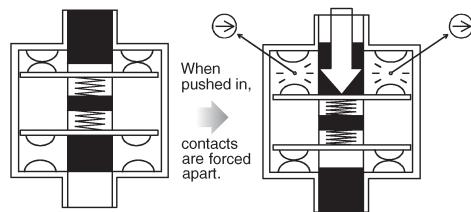


As seen above, the cam forces the N.C. contact up from the bottom, even if there is fusing of the contacts.

Note: Steel wire and spring rod types do not have positive opening mechanism.

● Slow-action BBM type

The slow action internal switch has N.C./N.O. electrically independent contacts (form Zb). The positive opening mechanism forces the contacts open (N.C. contacts only) even if they are fused.



■ SPECIFICATIONS

Standards	Compliance	Product-related: IEC 60947-5-1 \ominus , and EN 60947-5-1 \ominus Machine-related: IEC 60204-1 and EN 60204-1
	Certification	UL 508, CSA C22.2 No. 14
Structure	Protective structure	IP65 (IEC 60529, JIS C 0920)
	Electrical shock protection	Class II (IEC 61140)
	Pollution degree	3
	Internal switch	LJK-N21 $\square\square$ F12: snap action, LJK-N25 $\square\square$ F12 and LJK-N27 $\square\square$ F12: slow action (See Table 1.)
Electrical performance	Electrical rating	
	Insulation resistance	100 M Ω or more between terminals with the same polarity and between each terminal and non-live metal part (by DC500 megger)
	Initial contact resistance	25 m Ω or less (6 to 8 Vdc, thermal current 1A, measured by voltage drop method)
	Rated thermal current (Ith)	10A
	Short-circuit protection	10A breaking fuse, gG (gl) type
	Rated insulation voltage (Ui)	500V (IEC 60947-5-1), 300V (UL 508, CSA C22.2 No. 14)
	Rated conditional short-circuit current	1,000A
Mechanical performance	Rated impulse withstand voltage (Uimp)	6,000V
	Impact resistance	Durability: 500 m/s ² Note: 50 mm dia. resin adjustable roller lever types 150 m/s ² spring rod types 200 m/s ² IEC 60068-2-27
Life	Vibration resistance	250 m/s ² (10 to 500 Hz), IEC 60068-2-6 (See Table 2.)
	Max. operating speed and min. operating speed	10 million operations
Environment	Mechanical life	Snap action: 300000 operations, Slow action: 400000 operations
	Electrical life	-25 to +70°C (without freezing)
	Operating temperature	Max. 98% RH
Conduit	Operating humidity	-40 to +70°C
	Storage temperature	G 1/2
Recommended tightening torque		Body: 0.5 to 0.7 N·m (M4) Head: 0.8 to 1.2 N·m (M3 round head screw) Cover: 0.8 to 1.2 N·m (M3 round head screw) Terminal: 0.8 to 1.2 N·m (M3.5 round head screw) Lever: 1.3 to 1.7 N·m (M4 round head screw)

● Table 1. Electrical rating

AC-15: A300 (Ue=240V, le=3A)
DC-13: R300 (Ue=250V, le=0.1A)

Utilization categories AC-15: solenoid load

DC-13: solenoid load

Ue: rated operating voltage

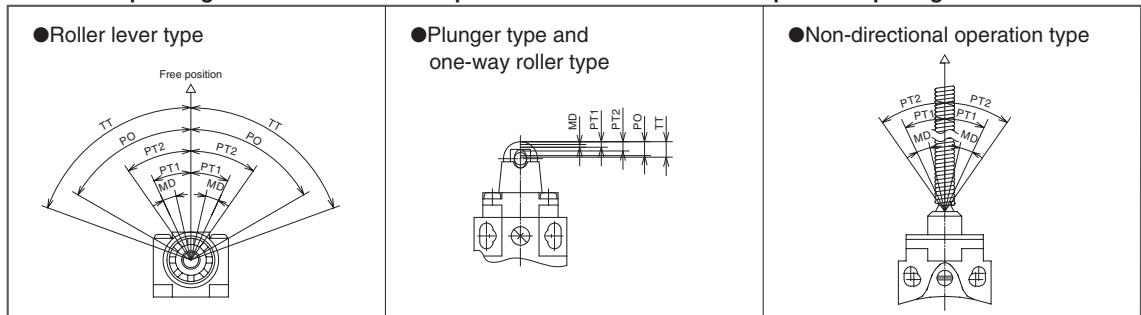
le: rated operating current

● Table 2. Max. operating speed and min. operating speed

Actuator	One-way roller / non-directional operation types				
	Roller lever type	Plunger type	One-way roller / non-directional operation types		
LJK-N2 $\square\square$ 18F12	LJK-N2 $\square\square$ 10F12	LJK-N2 $\square\square$ 21F12			
LJK-N2 $\square\square$ 39F12	LJK-N2 $\square\square$ 02F12	LJK-N2 $\square\square$ 27F12			
LJK-N2 $\square\square$ 45F12	LJK-N2 $\square\square$ 03F12	LJK-N2 $\square\square$ 06F12			
LJK-N2 $\square\square$ 49F12		LJK-N2 $\square\square$ 08F12			
Contact configuration	Min. speed	Max. speed	Min. speed	Max. speed	Min. speed
LJK-N21 $\square\square$ F12	0.03 m/min	1.5 m/s	0.01 m/min	0.5 m/s	0.02 m/min
LJK-N25 $\square\square$ F12	18 m/min	1.5 m/s	6 m/min	0.5 m/s	12 m/min
LJK-N27 $\square\square$ F12	18 m/min	1.5 m/s	6 m/min	0.5 m/s	12 m/min

■ OPERATING CHARACTERISTICS BY ROTARY OR IN-LINE ACTUATIONS OF ACTUATORS

O.F.: max. operating force needed for N.C. operation P.O.F: min. force for positive opening

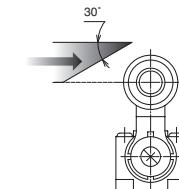
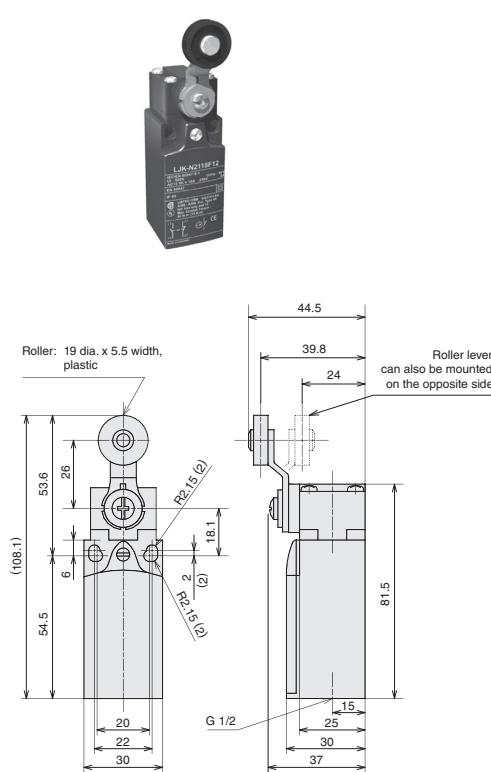


T.T.: total travel. P.T.1: pretravel for N.C. operation. P.T.2: pretravel for N.O. operation.
M.D.: minimum movement differential. P.O.: minimum travel to positive opening position.

■ SHAPE / DIMENSIONS / OPERATING CHARACTERISTICS / CIRCUIT DIAGRAMS

Resin roller lever: LJK-N2118F12, LJK-N2518F12, LJK-N2718F12

(unit: mm)



Operating characteristics by lever rotational angle	LJK-N2118F12	LJK-N2518F12	LJK-N2718F12
O.F. (max. operating force needed for N.C. operation)	0.1 N-m	0.1 N-m	0.1 N-m
P.O. (min. travel to positive opening position)	50°	47°	41°
P.O.F. (minimum force for positive opening)	0.15 N-m	0.15 N-m	0.15 N-m
PT1 (pretravel for N.C. operation)	(25°)	(28°)	(27°)
PT2 (pretravel for N.O. operation)	—	(38°)	—
MD	(16°)	—	—
TT (total travel)	(70°)	(70°)	(70°)

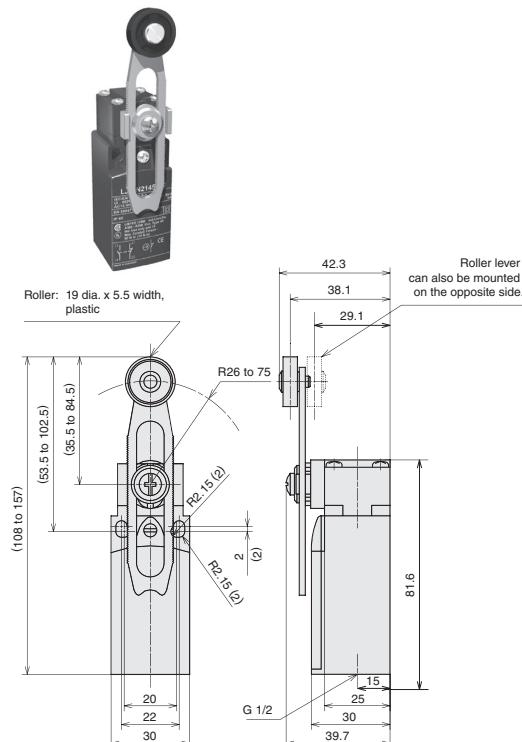
Catalog listing	Operating characteristics by dog operation	Circuit diagram									
LJK-N2118F12	<table border="1"> <tr> <td>21-22</td> <td>25°</td> <td>50°(P)</td> </tr> <tr> <td>13-14</td> <td>0°</td> <td>16°</td> </tr> <tr> <td>21-22</td> <td>70°</td> <td>—</td> </tr> </table>	21-22	25°	50°(P)	13-14	0°	16°	21-22	70°	—	
21-22	25°	50°(P)									
13-14	0°	16°									
21-22	70°	—									
LJK-N2518F12	<table border="1"> <tr> <td>21-22</td> <td>28°</td> <td>47°(P)</td> </tr> <tr> <td>13-14</td> <td>0°</td> <td>38°</td> </tr> <tr> <td>21-22</td> <td>70°</td> <td>—</td> </tr> </table>	21-22	28°	47°(P)	13-14	0°	38°	21-22	70°	—	
21-22	28°	47°(P)									
13-14	0°	38°									
21-22	70°	—									
LJK-N2718F12	<table border="1"> <tr> <td>11-12</td> <td>27°</td> <td>41°(P)</td> </tr> <tr> <td>21-22</td> <td>0°</td> <td>—</td> </tr> <tr> <td>11-12</td> <td>70°</td> <td>—</td> </tr> </table>	11-12	27°	41°(P)	21-22	0°	—	11-12	70°	—	
11-12	27°	41°(P)									
21-22	0°	—									
11-12	70°	—									

■ : Contacts closed □ : Contacts open (P): Min. travel to positive opening position

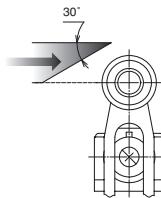
* Dimensional tolerance is ± 0.4 unless otherwise specified.

Resin adjustable roller lever: LJK-N2145F12, LJK-N2545F12, LJK-N2745F12

(unit: mm)



* Dimensional tolerance is ± 0.4 unless otherwise specified.

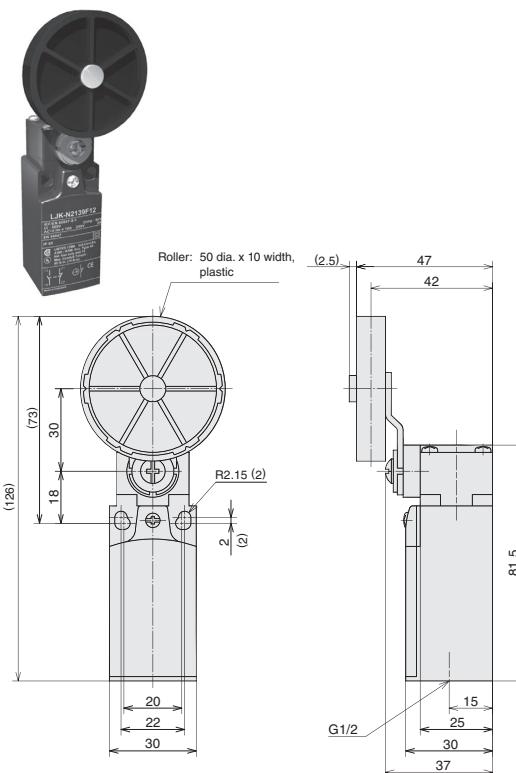


Operating characteristics by lever rotational angle	LJK-N2145F12	LJK-N2545F12	LJK-N2745F12
O.F. (max. operating force needed for N.C. operation)	0.1 N-m	0.1 N-m	0.1 N-m
P.O. (min. travel to positive opening position)	50°	47°	41°
P.O.F. (minimum force for positive opening)	0.15 N-m	0.15 N-m	0.15 N-m
PT1 (pretravel for N.C. operation)	(25°)	(28°)	(27°)
PT2 (pretravel for N.O. operation)	—	(38°)	—
MD	(16°)	—	—
TT (total travel)	(70°)	(70°)	(70°)

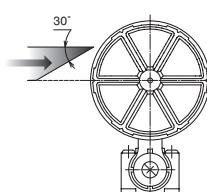
Catalog listing	Operating characteristics by dog operation	Circuit diagram												
LJK-N2145F12	<table border="1"> <tr> <td>21-22</td> <td>25°</td> <td>50°(P)</td> </tr> <tr> <td>13-14</td> <td></td> <td></td> </tr> <tr> <td>21-22</td> <td></td> <td></td> </tr> <tr> <td>13-14</td> <td>0°</td> <td>16° 70°</td> </tr> </table>	21-22	25°	50°(P)	13-14			21-22			13-14	0°	16° 70°	
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11-12	27°	41°(P)												
21-22														
11-12	0°	70°												

■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

50 mm dia. resin roller lever: LJK-N2139F12, LJK-N2539F12, LJK-N2739F12



* Dimensional tolerance is ± 0.4 unless otherwise specified.



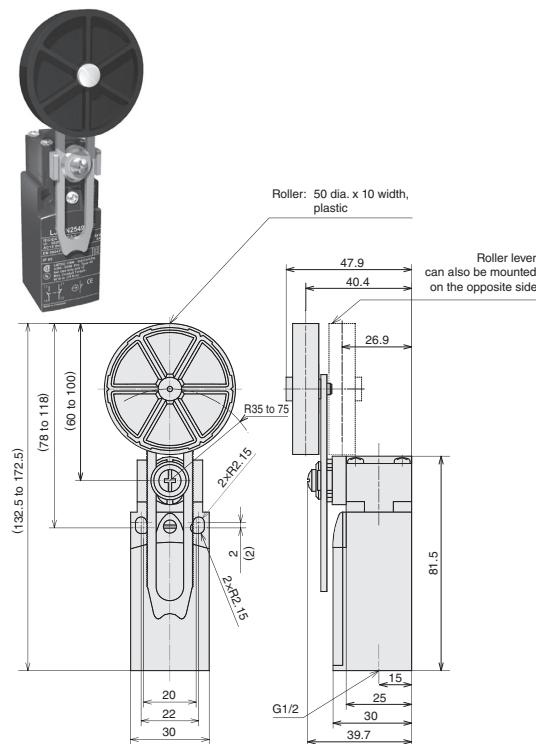
Operating characteristics by lever rotational angle	LJK-N2139F12	LJK-N2539F12	LJK-N2739F12
O.F. (max. operating force needed for N.C. operation)	0.1 N-m	0.1 N-m	0.1 N-m
P.O. (min. travel to positive opening position)	50°	47°	41°
P.O.F. (minimum force for positive opening)	0.15 N-m	0.15 N-m	0.15 N-m
PT1 (pretravel for N.C. operation)	(25°)	(28°)	(27°)
PT2 (pretravel for N.O. operation)	—	(38°)	—
MD	(16°)	—	—
TT (total travel)	(70°)	(70°)	(70°)

Catalog listing	Operating characteristics by dog operation	Circuit diagram												
LJK-N2139F12	<table border="1"> <tr> <td>21-22</td> <td>25°</td> <td>50°(P)</td> </tr> <tr> <td>13-14</td> <td></td> <td></td> </tr> <tr> <td>21-22</td> <td></td> <td></td> </tr> <tr> <td>13-14</td> <td>0°</td> <td>16° 70°</td> </tr> </table>	21-22	25°	50°(P)	13-14			21-22			13-14	0°	16° 70°	
21-22	25°	50°(P)												
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13-14	0°	16° 70°												
LJK-N2539F12	<table border="1"> <tr> <td>21-22</td> <td>28°</td> <td>47°(P)</td> </tr> <tr> <td>13-14</td> <td></td> <td></td> </tr> <tr> <td>21-22</td> <td>0°</td> <td>38° 70°</td> </tr> </table>	21-22	28°	47°(P)	13-14			21-22	0°	38° 70°				
21-22	28°	47°(P)												
13-14														
21-22	0°	38° 70°												
LJK-N2739F12	<table border="1"> <tr> <td>11-12</td> <td>27°</td> <td>41°(P)</td> </tr> <tr> <td>21-22</td> <td></td> <td></td> </tr> <tr> <td>11-12</td> <td>0°</td> <td>70°</td> </tr> </table>	11-12	27°	41°(P)	21-22			11-12	0°	70°				
11-12	27°	41°(P)												
21-22														
11-12	0°	70°												

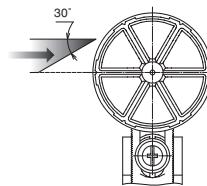
■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

50 mm dia. resin adjustable roller lever: LJK-N2149F12, LJK-N2549F12, LJK-N2749F12

(unit: mm)



* Dimensional tolerance is ± 0.4 unless otherwise specified.

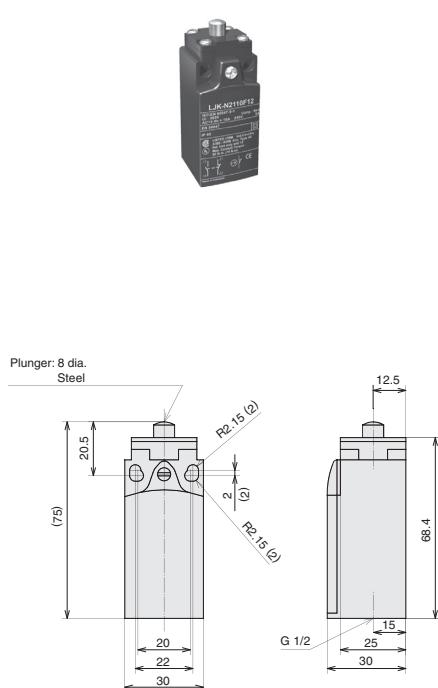


Operating characteristics by lever rotational angle	LJK-N2149F12	LJK-N2549F12	LJK-N2749F12
O.F. (max. operating force needed for N.C. operation)	0.1 N-m	0.1 N-m	0.1 N-m
P.O. (min. travel to positive opening position)	50°	47°	41°
P.O.F. (minimum force for positive opening)	0.15 N-m	0.15 N-m	0.15 N-m
PT1 (pretravel for N.C. operation)	(25°)	(28°)	(27°)
PT2 (pretravel for N.O. operation)	—	(38°)	—
MD	(16°)	—	—
TT (total travel)	(70°)	(70°)	(70°)

Catalog listing	Operating characteristics by dog operation	Circuit diagram
LJK-N2149F12		
LJK-N2549F12		
LJK-N2749F12		

■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

Plunger: LJK-N2110F12, LJK-N2510F12, LJK-N2710F12



* Dimensional tolerance is ± 0.4 unless otherwise specified.



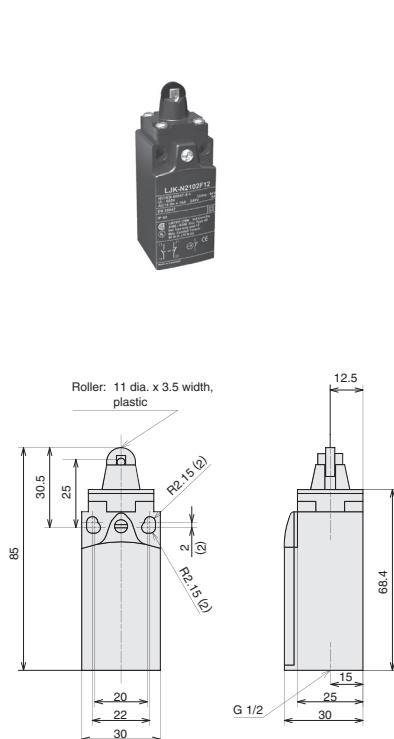
Operating characteristics by vertical operation	LJK-N2110F12	LJK-N2510F12	LJK-N2710F12
O.F. (max. operating force needed for N.C. operation)	15 N	15 N	15 N
P.O. (min. travel to positive opening position)	4.5 mm	4.2 mm	4.1 mm
P.O.F. (minimum force for positive opening)	30 N	30 N	30 N
PT1 (pretravel for N.C. operation)	(2.5 mm)	(2.8 mm)	(2.7 mm)
PT2 (pretravel for N.O. operation)	—	(4.0 mm)	—
MD	(1.4 mm)	—	—
TT (total travel)	(5.5 mm)	(5.5 mm)	(5.5 mm)

Catalog listing	Operating characteristics by vertical operation	Circuit diagram
LJK-N2110F12		
LJK-N2510F12		
LJK-N2710F12		

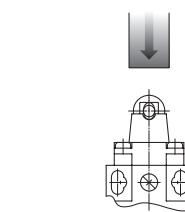
■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

Resin roller plunger: LJK-N2102F12, LJK-N2502F12, LJK-N2702F12

(unit: mm)



* Dimensional tolerance is ± 0.4 unless otherwise specified.

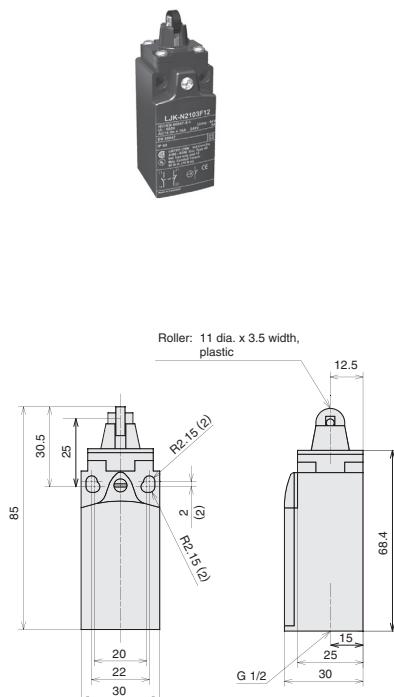


	Operating characteristics by vertical operation	LJK-N2102F12	LJK-N2502F12	LJK-N2702F12
O.F. (max. operating force needed for N.C. operation)	15 N	15 N	15 N	
P.O. (min. travel to positive opening position)	4.5 mm	4.2 mm	4.1 mm	
P.O.F. (minimum force for positive opening)	30 N	30 N	30 N	
PT1 (pretravel for N.C. operation)	(2.5 mm)	(2.8 mm)	(2.7 mm)	
PT2 (pretravel for N.O. operation)	—	(4.0 mm)	—	
MD	(1.4 mm)	—	—	
TT (total travel)	(5.5 mm)	(5.5 mm)	(5.5 mm)	

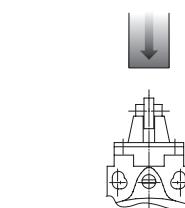
Catalog listing	Operating characteristics by vertical operation	Circuit diagram
LJK-N2102F12	 21-22: 2.5 mm, 4.5(P) 13-14: 0°, 1.4 mm, 5.5 mm	
LJK-N2502F12	 21-22: 2.8 mm, 4.2(P) 13-14: 0°, 4.0 mm, 5.5 mm	
LJK-N2702F12	 11-12: 2.7 mm, 4.1(P) 21-22: 0°, 5.5 mm	

■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

Resin cross roller plunger: LJK-N2103F12, LJK-N2503F12, LJK-N2703F12



* Dimensional tolerance is ± 0.4 unless otherwise specified.



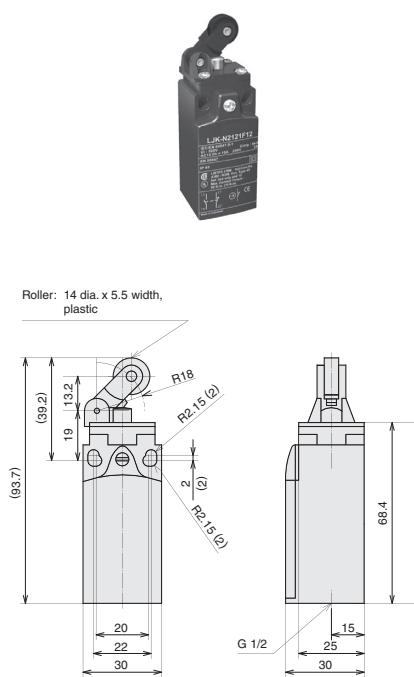
	Operating characteristics by vertical operation	LJK-N2103F12	LJK-N2503F12	LJK-N2703F12
O.F. (max. operating force needed for N.C. operation)	15 N	15 N	15 N	
P.O. (min. travel to positive opening position)	4.5 mm	4.2 mm	4.1 mm	
P.O.F. (minimum force for positive opening)	30 N	30 N	30 N	
PT1 (pretravel for N.C. operation)	(2.5 mm)	(2.8 mm)	(2.7 mm)	
PT2 (pretravel for N.O. operation)	—	(4.0 mm)	—	
MD	(1.4 mm)	—	—	
TT (total travel)	(5.5 mm)	(5.5 mm)	(5.5 mm)	

Catalog listing	Operating characteristics by vertical operation	Circuit diagram
LJK-N2103F12	 21-22: 2.5 mm, 4.5(P) 13-14: 0°, 1.4 mm, 5.5 mm	
LJK-N2503F12	 21-22: 2.8 mm, 4.2(P) 13-14: 0°, 4.0 mm, 5.5 mm	
LJK-N2703F12	 11-12: 2.7 mm, 4.1(P) 21-22: 0°, 5.5 mm	

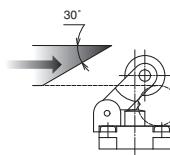
■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

Resin one-way roller (horizontal): LJK-N2121F12, LJK-N2521F12, LJK-N2721F12

(unit: mm)



* Dimensional tolerance is ± 0.4 unless otherwise specified.

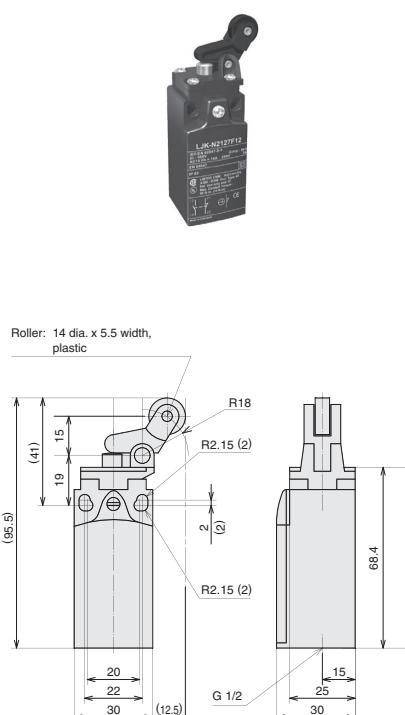


Operating characteristics by dog operation	LJK-N2121F12	LJK-N2521F12	LJK-N2721F12
O.F. (max. operating force needed for N.C. operation)	6 N	6 N	6 N
P.O. (min. travel to positive opening position)	15.9 mm	14.9 mm	14.6 mm
P.O.F. (minimum force for positive opening)	10 N	10 N	10 N
PT1 (pretravel for N.C. operation)	(9 mm)	(10 mm)	(9.6 mm)
PT2 (pretravel for N.O. operation)	—	(14.1 mm)	—
MD	(5.2 mm)	—	—
TT (total travel)	—	—	—

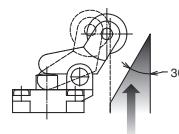
Catalog listing	Operating characteristics by dog operation	Circuit diagram
LJK-N2121F12		
LJK-N2521F12		
LJK-N2721F12		

■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

Resin one-way roller (vertical): LJK-N2127F12, LJK-N2527F12, LJK-N2727F12



* Dimensional tolerance is ± 0.4 unless otherwise specified.



Operating characteristics by dog operation	LJK-N2127F12	LJK-N2527F12	LJK-N2727F12
O.F. (max. operating force needed for N.C. operation)	6 N	6 N	6 N
P.O. (min. travel to positive opening position)	15.9 mm	14.9 mm	14.6 mm
P.O.F. (minimum force for positive opening)	10 N	10 N	10 N
PT1 (pretravel for N.C. operation)	(9 mm)	(10 mm)	(9.6 mm)
PT2 (pretravel for N.O. operation)	—	(14.1 mm)	—
MD	(5.2 mm)	—	—
TT (total travel)	—	—	—

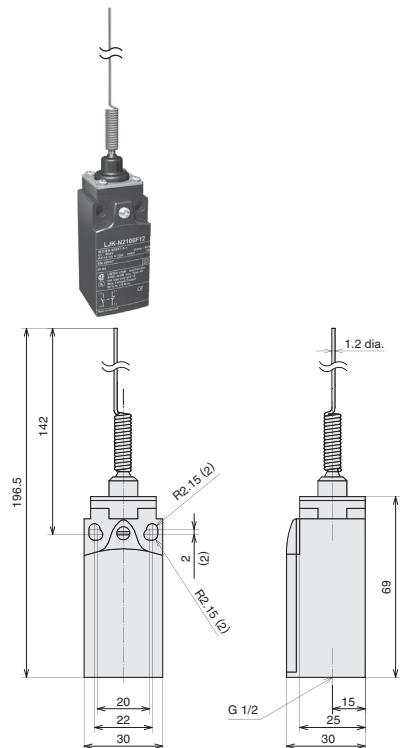
Catalog listing	Operating characteristics by dog operation	Circuit diagram
LJK-N2127F12		
LJK-N2527F12		
LJK-N2727F12		

■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

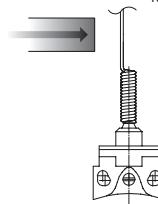
Steel wire: LJK-N2106F12, LJK-N2506F12, LJK-N2706F12

(unit: mm)

Note: Steel wire switches do not have positive opening mechanism.



* Dimensional tolerance is ± 0.4 unless otherwise specified.



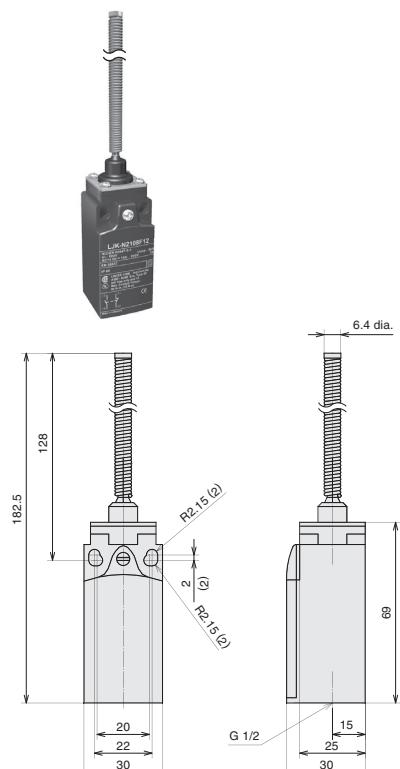
Operating characteristics by wire inclination angle	LJK-N2106F12	LJK-N2506F12	LJK-N2706F12
O.F. (max. operating force needed for N.C. operation)	0.13 N-m	0.13 N-m	0.13 N-m
P.O. (min. travel to positive opening position)	—	—	—
P.O.F. (minimum force for positive opening)	—	—	—
PT1 (pretravel for N.C. operation)	(25°)	(28°)	(27°)
PT2 (pretravel for N.O. operation)	—	(40°)	—
MD	(15°)	—	—
TT (total travel)	—	—	—

Catalog listing	Operating characteristics by dog operation	Circuit diagram
LJK-N2106F12		
LJK-N2506F12		
LJK-N2706F12		

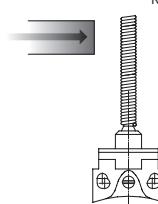
■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

Spring rod: LJK-N2108F12, LJK-N2508F12, LJK-N2708F12

Note: Steel wire switches do not have positive opening mechanism.



* Dimensional tolerance is ± 0.4 unless otherwise specified.



Operating characteristics by rod inclination angle	LJK-N2108F12	LJK-N2508F12	LJK-N2708F12
O.F. (max. operating force needed for N.C. operation)	0.13 N-m	0.13 N-m	0.13 N-m
P.O. (min. travel to positive opening position)	—	—	—
P.O.F. (minimum force for positive opening)	—	—	—
PT1 (pretravel for N.C. operation)	(25°)	(28°)	(27°)
PT2 (pretravel for N.O. operation)	—	(40°)	—
MD	(15°)	—	—
TT (total travel)	—	—	—

Catalog listing	Operating characteristics by dog operation	Circuit diagram
LJK-N2108F12		
LJK-N2508F12		
LJK-N2708F12		

■: Contacts closed □: Contacts open (P): Min. travel to positive opening position

HANDLING PRECAUTIONS

1. Mounting the switch

- Always tighten each part of the safety switch to the tightening torque recommended in the product specifications. If any part is tightened excessively, the screw and/or other parts may be damaged.
- Mount the dog so that no force is directly applied to the actuator in the free state.
- Do not use any glue or lubricant containing silicone. Doing so might result in faulty electrical conductivity.

2. Wiring

- Do not perform wiring work with the power turned ON. Doing so might cause an electrical shock or cause the device to operate suddenly.

3. Adjustment

- Do not apply excessive force (force 5 times larger than the O.F.) to the actuator when it is beyond the operation limit position. Doing so might break the switch.
- Adjust the actuator motion so that it exceeds the specified P.O. (travel to positive opening position) but does not exceed the operation limit position.

4. Operating environment

- Do not use in a location subject to splashing with strong acid or alkali.

Before use, thoroughly read the “Precautions for use” and “Precautions for handling” in the Technical Guide on pages **D-111** to **D-122** as well as the instruction manual and product specification for this switch.